

Koike Cho 44-1, Meito Ku, Nagoya, 465-0047, Japan

💌 ravi2008joshi@gmail.com | 🏕 www.ravijoshi.xyz | 🖸 ravijo | 🛅 ravi2008joshi | 👪 Ravi P. Joshi | 📵 ORCiD

Technical Skills

Denso Robotics@ 6-axis and 4-axis Manipulators, Universal Robots@ UR5e, Rethink Robotics@ Baxter, **Commercial Robot Used**

Toyota© HSR, KUKA Robotics© KR 5

Programming C/C++, Python, PACScript, C#, Embedded C, Java, KUKA Robot Language

Tools/Libraries ROS, TensorRT, Keras, PyTorch, TensorFlow, PyBullet, ØMQ, PCL, OpenCV, Protocol Buffers, ETFX, MATLAB

Microsoft Visual Studio, Eclipse, NetBeans, WinAVR

Web Drupal, HTML, PHP, JS, JSF

OS Platform WINDOWS (XP, 8 and 10), LINUX (Ubuntu)

Patent

• Automatic Dishwashing System and Storage Medium. Publication No.: WO/2021/006306

Experience 10 Yrs (5 Yrs Research + 5 Yrs Industry)

TechMagic Corporation Nagoya, Japan SENIOR ROBOTICS ENGINEER Dec. 2020 - Ongoing

• Designing efficient strategies for food picking for an in-house invented gripper.

- Building and investigating CNN-based models for accurate food picking.
- · TensorRT implementation for real-time instance segmentation on the NVIDIA Jetson device.
- Developing a module for container position estimation using an F/T sensor in a workspace shared between 6-axis and 4-axis manipulators.

OMRON SINIC X Corporation

Tokyo, Japan

INTERNSHIP

Apr. 2020 - Jun. 2020

- · Worked on learning from successful and failed behaviors with a tactile device and soft robot.
- · Developed a multimodal learning system to compute a neural network-based latent representation and then utilize it in Deep Reinforcement Learning for the policy learning.

Indian Institute of Technology (IIT) Delhi

New Delhi, India May 2014 - Aug. 2015

SENIOR RESEARCH FELLOW

- Worked on the force control of a KUKA robot to perform the task of inserting a peg in a hole having clearance of 0.1 mm.
- Development of RoboAnalyzer software which helps in teaching and learning of robot kinematics and dynamics in an easier and funnier way.

Indian Institute of Technology (IIT) Delhi

New Delhi, India

PROJECT STAFF

Feb. 2014 - May 2014

- Developed a collaborative project "SAKSHAR: An Image-projective Desktop Varnamala Trainer (IDVT) for interactive learning of alphabets".
- The project aims to make primary education more attractive and fun towards the kids.

Altair Engineering Bangalore, India

SOFTWARE QA ENGINEER

Jun. 2012 - Jan. 2014

- · Successfully performed software testing such as performance testing, load testing, and functional testing of Altair Web Portal Framework and Compute Manager, a web-based interface for PBS workload manager.
- In charge of guaranteeing the licensing and other critical functionalities of the Altair Web Portal Framework.
- · Developed a framework for automated testing of REST Services.

Reviewers_

: Russian Journal of Nonlinear Dynamics (RJND), ISSN: 2658-5324 2022

2022 : International Conference on Nonlinearity, Information and Robotics (NIR)

2022 : IEEE International Conference on Robotics and Automation (ICRA)

: IEEE IEEE Robotics and Automation Letters (RA-L) 2022

2020 : IEEE International Conference on Robotics and Automation (ICRA) 2020 : IEEE-RAS International Conference on Humanoid Robots (Humanoids) 2020 : Computer Applications in Engineering Education(CAE), ISSN: 1099-0542 2019

: IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

Lectures

| 2022 | : VIT-AP University 🗹 | Vijayawada, India |
|------|---|--------------------|
| 2022 | : National Institute of Technology Patna 🗹 | Patna, India |
| 2022 | : Robotics@Ireland 🗹 | Dublin, Ireland |
| 2022 | : Indian Institute of Information Technology, Design and Manufacturing, Jabalpur 🗹 | MP, India |
| 2022 | : Adamas University | Kolkata, India |
| 2022 | : Karmaveer Kakasaheb Wagh Institute of Engineering Education & Research, Nashik 🗹 | Maharashtra, India |
| 2021 | : I-Hub Foundation for Cobotics (A Joint initiative of IIT Delhi and DST, Govt. of India) 🗹 | Delhi, India |

Projects

Robotic Clothing Assistance

Kitakyushu, Japan

Kyushu Institute of Technology

Oct. 2015 - Nov. 2020

- · Robotic solutions for clothing assistance can significantly improve the quality of life of the elderly.
- Developed a robotic system using a dual-arm Baxter robot to assist the elderly in getting them dressed up.
- · Proposed a framework for robotic clothing assistance by imitation learning from a human demonstration to a compliant dual-arm robot.

Adaptive Force Control of an Industrial Robot Equipped with F/T sensor 🗹

New Delhi, India

INDIAN INSTITUTE OF TECHNOLOGY DELHI

May. 2014 - Aug. 2015

- The goal was to design and implement control mechanism for KUKA KR5 industrial robot.
- Performed object manipulation like putting cylindrical pellet into hollow cylindrical tube based on the force feedback.

SAKSHAR 🗗 New Delhi, India

Indian Institute of Technology Delhi

May. 2014 - Aug. 2015

- Designed to improve the learning of alphabets, etc. for children through an interactive audio visual feedback system.
- · Used a projector and a LiDAR sensor to render a virtual display, which permits production of large interactive displays with minimal cost.

RoboAnalyzer 🗹 New Delhi, India

Indian Institute of Technology Delhi

May. 2014 - Aug. 2015

- This is a software which helps in teaching and learning of robotics in an easy and fun way.
- Provides commonly used robot models to perform kinematics and dynamics analysis.
- Developed modules for file based I/O of robot data, migration from Tao to OpenTK, etc.

Truck driving simulator using Stewart platform ✓

New Delhi, India

Indian Institute of Technology Delhi

Mar. 2015 - Aug. 2015

- The goal was to design a truck driving simulator that can achieve any position and orientation in 3D space.
- Designed a controller for the physical simulator by implementing inverse kinematics of the Stewart platform.

Micro-mouse Simulation 🗹

Madhya Pradesh, India

Indian Institute of Information Technology Design & Manufacturing Jabalpur

Academic Year - 2012

- · Visual simulation of micro-mouse game.
- Random maze is designed by using DFS (Depth-first search) algorithm.
- Generated maze is solved by using A* search algorithm.

Design and Fabrication of USB2.0 to Multiport Connector

Madhya Pradesh, India

Indian Institute of Information Technology Design & Manufacturing Jabalpur

Academic Year - 2011

- A multipurpose adaptor to connect various peripheral devices.
- Supports all popular interfaces such as Serial, SATA, PATA, Ethernet, and PS2 via a USB2.0.

Microcontroller-based Line Follower Robot

Madhya Pradesh, India

INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN & MANUFACTURING JABALPUR

Academic Year - 2010

- The aim was to design a fully automated robot which can follow any curved path with appropriate speed.
- Central part of the robot contains an array of TSOP sensors and an AtMega-8 microcontroller.

CRUISADERS 🗹 Madhya Pradesh, India

Academic Year - 2010

INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN & MANUFACTURING JABALPUR

- The project was aimed for robot war event held in technical festival of Indian Institute of Technology Bombay, India.
- The robot was capable of extreme fight in battle.
- The heavy bot uses a rotating circular disk and momentum due to its internal inertia to destroy the opponent.

Publications

JOURNAL ARTICLES [3]

A Framework for Robotic Clothing Assistance by Imitation Learning Ravi P. Joshi, Nishanth Koganti, Tomohiro Shibata Advanced Robotics 33.22 (2019) pp. 1156-1174. Taylor & Francis DOI: 10.1080/01691864.2019.1636715 2019 Calibration and Statistical Techniques for Building an Interactive Screen for Learning of Alphabets by Children Riby A. Boby, Ravi P. Joshi, Subir K. Saha, Takafumi Matsumaru, Pratyusha Sharma, Siddhartha Jaitly International Journal of Advanced Robotic Systems 14.3 (2017) p. 1729881417703939. SAGE Publications London, UK DOI: 10.1177/1729881417703939 2017 Robot Kinematics Made Easy using RoboAnalyzer Software Ratan S. Othayoth, Rajeevlochana G. Chittawadigi, Ravi P. Joshi, Subir K. Saha Computer Applications in Engineering Education 25.5 (2017) pp. 669–680. Wiley Online Library DOI: 10.1002/cae.21828 2017 CONFERENCE PROCEEDINGS [13] Intelligent Wheelchair-Humanoid Robot Collaboration for Clothing Assistance of the Elderly Ravi P. Joshi, Jayant P. Tarapure, Tomohiro Shibata 13th International Conference on Human System Interaction (HSI) Tokyo, Japan DOI: 10.1109/HSI49210.2020.9142645 Quantitative Evaluation of Clothing Assistance using Whole-Body Robotic Simulator of the Elderly Ravi P. Joshi, Tomohiro Shibata, Kunihiro Ogata, Yoshio Matsumoto 28th IEEE International Conference on Robot and Human Interactive Communication (RO-MAN) New Delhi, India DOI: 10.1109/RO-MAN46459.2019.8956308 Mouse Anatomical Cardinal Planes and Axes Towards Augmentation for Behavior Analysis Salvador B. Negrete, Ravi P. Joshi, Rollyn Labuguen, Jumpei Matsumoto, Tomohiro Shibata Joint 7th International Conference on Informatics, Electronics Vision (ICIEV) and 2nd International Conference on Kitakyushu, Japan Imaging, Vision Pattern Recognition (icIVPR) DOI: 10.1109/ICIEV.2018.8641000 Robotic Cloth manipulation for Clothing Assistance Task using Dynamic Movement Primitives Ravi P. Joshi, Nishanth Koganti, Tomohiro Shibata Proceedings of the Conference on Advances in Robotics (AiR) New Delhi, India DOI: 10.1145/3132446.3134878 2017 Estimating 3D Hand Location for Clothing Assistance Initialization Using Dynamic Movement Primitives Ravi P. Joshi, Rithul Perathara, Rolyn Labuguen, Nishanth Koganti, Tomohiro Shibata Proceedings of the 35th Annual Conference of Robotics Society of Japan Kawagoe, Japan URL: http://rsj2017.rsj-web.org/RSJ2017_pg02.pdf A Study on Human-Robot Collaboration for Table-setting Task Krati Saxena, Rollyn Labuguen, Ravi P. Joshi, Nishanth Koganti, Shibata Tomohiro IEEE International Conference on Robotics and Biomimetics (ROBIO) Macau, China DOI: 10.1109/ROBIO.2017.8324415 2017 Cloth Extremity Detection from a Clutter of Clothes using Bayesian GPLVM Vishal Gaurav, Nishanth Koganti, Riku Nakata, Ravi P. Joshi, Tomohiro Shibata International session on Robotics, Mechatronics and Control, Robotics Society of Japan Yamagata, Japan 2016 URL: http://rsj2016.rsj-web.org/data/RSJ2016_pg.pdf Motor-skill Learning in Latent Spaces for Robotic Clothing Assistance Nishanth Koganti, Ravi P. Joshi, Tomoya Tamei, Tomohiro Shibata, Kazushi Ikeda Proceedings of the 34th Annual Conference of Robotics Society of Japan URL: http://rsj2016.rsj-web.org/data/RSJ2016_pg.pdf 2016 Virtual Experiments for Integrated Teaching and Learning of Robot Mechanics using RoboAnalyzer Ratan Sadanand, Ravi P. Joshi, Rajeevlochana G. Chittawadigi, Subir K. Saha Kolaghat, India 28th International Conference on CAD/CAM, Robotics and Factories of the Future ISBN: 978-81-322-2740-3 2016 Force Control of Robot Manipulator using Industrial Servo Drives Arun D. Udai, Subir K. Saha, Ravi P. Joshi, Rattan Sadanand Ranchi, India International Conference on Evolution in Manufacturing (ICEM) ISBN: 978-93-86256-11-9 2016 Virtual Robots Module: An Effective Visualization Tool for Robotics Toolbox Ratan Sadanand, Rajeevlochana G. Chittawadigi, Ravi P. Joshi, Subir K. Saha Proceedings of the Conference on Advances In Robotics DOI: 10.1145/2783449.2783475 2015 Projectable Interactive Surface using Microsoft Kinect v2: Recovering Information from Coarse Data to Detect Touch Pratyusha Sharma, Ravi P. Joshi, Riby A. Boby, Subir K. Saha, Takafumi Matsumaru IEEE/SICE International Symposium on System Integration (SII) Nagoya, Japan DOI: 10.1109/SII.2015.7405081 Depth-based Localization for Robotic Peg-in-Tube Assembly Arun D. Udai, Ravi P. Joshi, Subir K. Saha Hamburg, Germany IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) DOI: 10.1109/IROS.2015.7353871

PRESENTED (UNPUBLISHED) [6] A Study on the Electric Wheelchair-Humanoid Collaboration for Clothing Assistance of the Elderly Ravi P. Joshi, Jayant P. Tarapure, Tomohiro Shibata Macau, China Late Breaking Results at IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) URL: https://www.iros2019.org/LBRposter 2019 Extremity Detection from a Pile of Garments using Bayesian GPLVM Vishal Gaurav, Nishanth Koganti, Riku Nakata, Ravi P. Joshi, Tomohiro Shibata Workshop on Assistive and Service Robotics in a Human Environment, IEEE/RSJ International Conference on Intelligent Daejeon, Korea Robots and Systems (IROS) URL: https://research02.jimu.kyutech.ac.jp/html/100000703_knkyu_prsn_en.html 2016 Robotic Cloth Manipulation for Clothing Assistance Task using Dynamic Movement Primitives Ravi P. Joshi, Nishanth Koganti, Tomohiro Shibata 4th International Symposium on Applied Engineering and Sciences (SAES) Tobata, Japan URL: http://www.life.kyutech.ac.jp/~saes2016/SAES3.html 2016 Use of Kinect Sensor for Building an Interactive Device Ravi P. Joshi, Pratyusha Sharma, Riby A. Boby, Subir K. Saha, Takafumi Matsumaru 10th International collaboration Symposium on Information, Production and Systems (ISIPS) Kitakvushu, Japan URL: http://www.waseda.jp/assoc-ics/2016/program.html 2016 SAKSHAR: An Image-projective Desktop Varnamala Trainer (IDVT) for Interactive Learning of Alphabets Ravi P. Joshi, Riby A. Boby, Subir K. Saha, Takafumi Matsumaru Developing Countries Forum, IEEE International Conference on Robotics and Automation (ICRA) Washington, USA $\verb|URL:| http://icra2015.org/conference/forums/11-conference/37-developing-countries-forum| | Conference/100 | Conference/10$ SAKSHAR: An Image-projective Desktop Varnamala Trainer (IDVT) for Interactive Learning of Alphabets Ravi P. Joshi, Riby A. Boby, Subir K. Saha, Takafumi Matsumaru 8th International collaboration Symposium on Information, Production and Systems (ISIPS) Kitakyushu, Japan

Education

Kyushu Institute of Technology (KyuTech) Wakamatsu

URL: http://www.waseda.jp/assoc-ics/2014/program.html

Kitakyushu, Japan

DOCTOR OF PHILOSOPHY IN MACHINE LEARNING IN ROBOTICS

Sep. 2020

• THESIS TITLE: Design and Development of a Dual-arm Robotic Clothing Assistance System using Imitation Learning

Kyushu Institute of Technology (KyuTech) Wakamatsu

Kitakyushu, Japan

MASTER OF ENGINEERING IN MACHINE LEARNING IN ROBOTICS

Sep. 2017

2014

Major Project: Clothing Assistance using DMP

Indian Institute of Information Technology Design & Manufacturing (IIITDM) Jabalpur

Madhya Pradesh, India

BACHELOR OF TECHNOLOGY IN COMPUTER SCIENCE & ENGINEERING

Aug. 2012

Jun. 2007

MAJOR PROJECT: Data Structure Simulator

Hargovind Suyal Saraswati Vidya Mandir Inter College (HGSSVMIC) Haldwani

Uttarakhand, India

INTERMEDIATE EXAMINATION

• MAJOR SUBJECTS: Maths, Physics and Chemistry

Hargovind Suyal Saraswati Vidya Mandir Inter College (HGSSVMIC) Haldwani

Uttarakhand, India

HIGH SCHOOL EXAMINATION Jun. 2005

Personal Information

Date of Birth August 5, 1990

Languages Hindi, English, Japanese (Beginner)

Honors & Awards

| 2020 | Advanced Robotics Excellent Paper Award by Robotics Society of Japan (RSJ) | Japan |
|------|---|-------|
| 2020 | Best Paper – Finalists Award in 13th International Conference on Human System Interaction (HSI) | Japan |
| 2017 | First Prize in HEBI Robotics Hackathon at KyuTech | Japan |
| 2016 | Excellent Paper Award in 10th International collaboration Symposium on IPS at Waseda University | Japan |
| 2015 | MEXT Scholarship by Ministry of Education, Culture, Sports, Science and Technology of Japan | Japan |
| 2015 | Successfully Completing Mechanics of Robots in Classroom course by Prof. S. K. Saha, IIT Delhi | India |
| 2015 | MOOC on Image Processing by Prof. G. Sapiro, Duke University, USA | India |
| 2012 | MOOC on Computer Networks by Prof. N. McKeown, Stanford University, USA | India |

Media Coverage _____

| 2022 | M-Robo: World's first robot for serving sticky side dishes with high accuracy ☑ | Japan | |
|------|---|-------|--|
| 2021 | W-Robo : finibo has been installed successfully at ANAC Tokyo Airport (Haneda) factory ☑ | Japan | |
| 2021 | Voice of Graduate : KYUTECH TIMES, Kyushu Institute of Technology ☑ | Japan | |
| 2020 | HSI Research Work : WHILL Co., Ltd. ☑ | Japan | |
| 2019 | iREX Exhibition: World Business Satellite (WBS) TV, Live News Alpha (Fuji TV), Ann News (Asahi TV), MIA | lanan | |
| | (Nippon TV), Super J Channel (Asahi TV) 🗷 | Japan | |
| 2019 | Lab Visit : Nishi Nippon Japanese Newspaper ☑ | Japan | |
| 2018 | Kokura Exhibition : Kyushu Asahi Broadcasting (KBC) TV, Radio Kyushu Broadcasting (RKB) TV, Nikkei | Japan | |
| | Japanese Newspaper 🗷 | | |
| 2017 | iREX Exhibition : Nippon Hoso Kyokai (NHK) TV, World Business Satellite (WBS) TV ☑ | Japan | |
| 2017 | Lab Visit : DNA Mumbai Newspaper ☑ | India | |